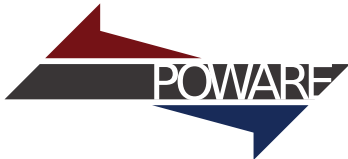


The eWoms Module: A Primer

Andreas Lauser

October 19, 2017



Intended subject of this talk:

- High-level overview of the simulator part of the OPM code base for C++ developers
- Focus on the core of the numerical framework, i.e., the eWoms module

This talk is **not**:

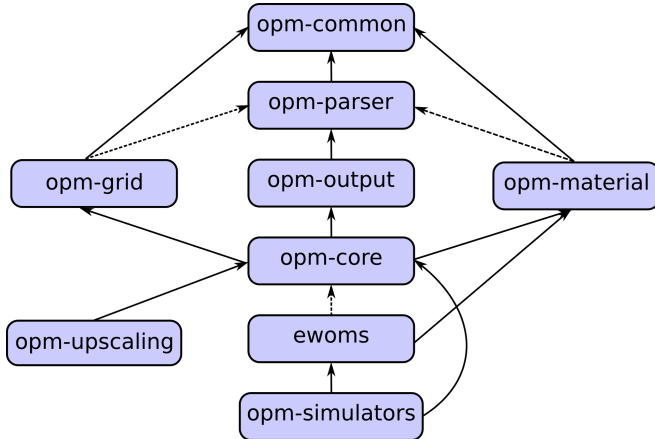
- An introduction to programming, C++, the DUNE framework, etc.
 - Some familiarity assumed
- A guide for implementing \$YOUR_FAVOURITE_FEATURE
 - Commercial support available
- A tutorial
- A detailed discussion of the technicalities

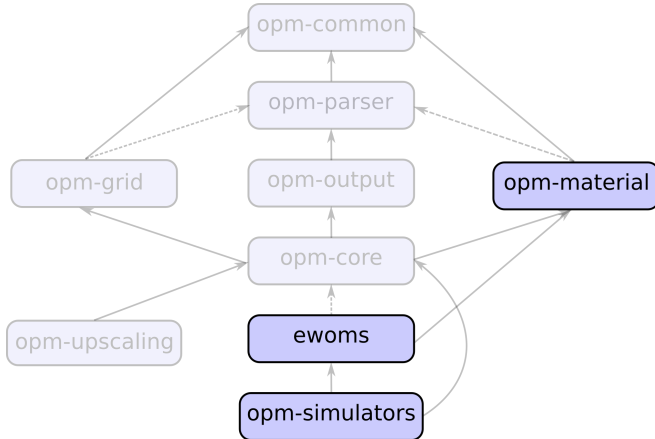
Part I

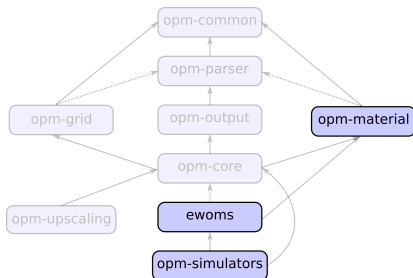
The Zoom-in

- 1 OPM: The View From Space
- 2 eWoms: A Birdseye View
- 3 Close Up: The Immiscible Model
- 4 Microscope: The Energy Extension

- 1 OPM: The View From Space
- 2 eWoms: A Birdseye View
- 3 Close Up: The Immiscible Model
- 4 Microscope: The Energy Extension

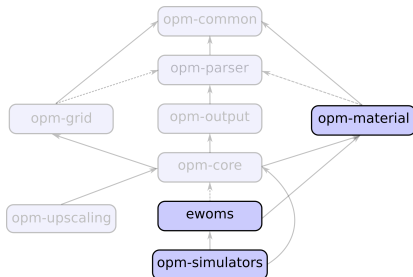






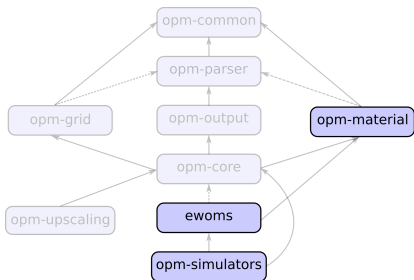
opm-material implements thermodynamic multi-phase relations as well as constitutive relations, e.g.:

- Thermodynamic representations (`FluidStates`)
- Thermodynamic properties (`FluidSystems`)
- Capillary-pressure & relative permeability relations (“material laws”)
- Solvers for non-linear thermodynamic systems of equations (constraint solvers, e.g. flash)



eWoms provides a versatile, extensible and performant numerical framework:

- Models for conservation equations
- Spatial and temporal discretization schemes
- Linear and non-linear solvers



opm-simulators features end-user ready simulator programs:

- In particular, the *flow* simulator for ECL decks
- (This module is currently undergoing a transition, many things do actually belong someplace else)



Most of the numerics of flow is implemented by the framework layer, i.e., the eWoms module!

- 1 OPM: The View From Space
- 2 **eWoms: A Birdseye View**
- 3 Close Up: The Immiscible Model
- 4 Microscope: The Energy Extension

High level control flow:

Time loop

Non-linear solve

Linearize

Compute local t.d. state

Calculate local residual

Linear solve

Update

```
Simulator::run()  
NewtonMethod::apply()  
  
FvBaseLinearizer::linearize()  
  
$MODELIntensiveQuantities::update()  
  
$MODELLocalResidual::computeStorage()  
$MODELLocalResidual::computeFlux()  
$MODELLocalResidual::computeSource()  
ParallelBiCGStabSolverBackend::solve()  
  
NewtonMethod::update()
```

Simulator High-level control of program execution, central “Nexus” for all information

Model Specifies the conservation equations, primary variables, etc. Also, spatial and temporal discretization

Problem Specifies the physical set-up

Specifies all externally “impressed” parameters:

- Initial solution
- Boundary conditions
- Porosity
- Intrinsic permeabilities
- Material-law parameters
- ...

Problems are concerned with specifying the **physical set-up** mostly independently of the selected model.

Time loop

Non-linear solve

Linearize

Compute local t.d. state

Calculate local residual

Linear solve

Update

```
Simulator::run ()  
NewtonMethod::apply ()  
FvBaseLinearizer::linearize ()  
$MODELIntensiveQuantities::update ()  
$MODELLocalResidual::computeStorage ()  
$MODELLocalResidual::computeFlux ()  
$MODELLocalResidual::computeSource ()  
ParallelBiCGStabSolverBackend::solve ()  
NewtonMethod::update ()
```

Wait a second: There's no problem here!

Time loop	<code>Simulator::run()</code>
Non-linear solve	<code>NewtonMethod::apply()</code>
Linearize	<code>FvBaseLinearizer::linearize()</code>
Compute local t.d. state	<code>\$MODELIntensiveQuantities::update()</code>
Calculate local residual	<code>\$MODELLocalResidual::computeStorage()</code> <code>\$MODELLocalResidual::computeFlux()</code> <code>\$MODELLocalResidual::computeSource()</code>
Linear solve	<code>ParallelBiCGStabSolverBackend::solve()</code>
Update	<code>NewtonMethod::update()</code>

Here it enters the picture!

- 1 OPM: The View From Space
- 2 eWoms: A Birdseye View
- 3 Close Up: The Immiscible Model**
- 4 Microscope: The Energy Extension

Models specify conservation equations. The “immiscible” model deals with M fluid phases and . . .

- . . . assumes that fluid phases are completely immiscible
- . . . conserves the mass in kg of each fluid phase
- . . . selects the pressure of the first phase plus the saturations of the first $M - 1$ phases as primary variables

Using the primary variables, compute everything else:

- Saturations of *all* fluid phases:

$$S_M = 1 - \sum_{\alpha=1}^{M-1} S_{\alpha}$$

- Pressures of *all* fluid phases using the reference phase' pressure and the capillary pressures:

$$p_{\alpha} = p_1 + p_{c,1 \rightarrow \alpha}$$

- Phase compositions
 - Already specified by assuming immiscibility
- Other quantities needed for the residual, e.g., ρ_{α} , μ_{α} , \mathbf{K}
- Thermodynamic relations computed opm-material or quantities directly provided by the problem

Based on the thermodynamic state, compute the residual for a degree of freedom:

- Storage: Mass in kg/m^3 for each phase at a given time t :

$$\sigma_{\alpha,t} = \phi_t \mathcal{S}_{\alpha,t} \rho_{\alpha,t}$$

- Fluxes: Mass in $kg/(m^2s)$ for a phase at a given time t :

$$\zeta_{\alpha,t} = -\rho_{\alpha,t} \frac{k_{r,\alpha,t}}{\mu_{\alpha,t}} \mathbf{K} \nabla (p_{\alpha,t} - g \rho_{\alpha,t})$$

- Source: Mass change in $kg/(m^3s)$; just forward the problem's $q_{\alpha,t}$

Generic code calculates the local residual for phase α :

$$r_{\alpha} = \frac{\sigma_{\alpha,t_2} - \sigma_{\alpha,t_1}}{t_2 - t_1} + \frac{1}{|\mathcal{V}|} \sum_{\partial\mathcal{V}} |\partial\mathcal{V}| \zeta_{\alpha,t_2} - \mathbf{q}_{\alpha,t_2}$$

(for the implicit Euler time- and a finite volume space discretization)

- 1 OPM: The View From Space
- 2 eWoms: A Birdseye View
- 3 Close Up: The Immiscible Model
- 4 **Microscope: The Energy Extension**

- Models can be extended generically
- Extension mechanism is cooperative
- Idea: Derive all classes from extension classes
 - Provide real and dummy implementations with same API
- Use callbacks in the base model
- Compiler optimizes dummy callbacks away


```
template <class TypeTag, bool enableEnergy>
class EnergyIntensiveQuantities;
```

```
template <class TypeTag>
class EnergyIntensiveQuantities<TypeTag, true>
{ // ...
    void updateEnergy()
    { /* ... */ }
    const Evaluation& heatCapacitySolid() const
    { return heatCapSolid_; }
};
```

```
template <class TypeTag>
class EnergyIntensiveQuantities<TypeTag, false>
{ // ...
    void updateEnergy()
    { }
    const Evaluation& heatCapacitySolid() const
    { OPM_THROW(std::logic_error, "Energy is not conserved"); }
};
```

```
template <class TypeTag>
class ImmiscibleIntensiveQuantities
: public EnergyIntensiveQuantities<TypeTag,
                                GET_PROP_VALUE (TypeTag,
                                                EnableEnergy)>
{
    typedef EnergyIntensiveQuantities<TypeTag, GET_PROP_VALUE (
        TypeTag, EnableEnergy)> EnergyIQ;
    // ...
    void update() { // ...
        EnergyIQ::updateEnergy();
    }
};
```

Same for the other classes which need to be aware of the extension. (Local residual, extensive quantities, output writing classes, ...)

The problem decides if energy is conserved by setting the `EnableEnergy` property

- If yes, it needs to provide some additional methods

```
SET_BOOL_PROP(Co2InjectionNiProblem, EnableEnergy, true);
```

Part II

Important Concepts

- 5 The Property System
- 6 The Parameter System
- 7 Validation against DuMu^x
- 8 Demo: ebos
- 9 Summary & Outlook

- 5 The Property System
- 6 The Parameter System
- 7 Validation against DuMu^X
- 8 Demo: ebos
- 9 Summary & Outlook

Idea: Use specialization to give generic template code the chance to take different code paths based on its template arguments

Example:

```
template <class T>
struct is_float { static const bool value = false; }

template <>
struct is_float<float> { static const bool value = true; }

template <class T>
void f(const T& x)
{ std::cout << is_float<T>::value?"float: ":"non-float: "
  << x <<std::endl; }

int main()
{ f(float(1.0)); f(std::string("foo")); return 0; }
```

- Observation: Class bodies are arbitrary
- Great! This can be (mis-)used to pass any number of compile time parameters using a single template parameter \mathbb{T} !
- Not so great: We might want to inherit these properties
 - eWoms simulators define about 150 parameters
- It might be nice to know which traits have been defined where and what their values are

- “C++ traits on steroids”: Same basic idea as C++ traits, but with inheritance and introspection
- Duct tape which holds the eWoms models together
- Slightly different terminology than C++ traits:

C++ Traits	eWoms property system
trait name	property tag
T (specialized-for type)	type tag
trait class body	property

- Macros to hide the template kung-fu

```
namespace Ewoms { namespace Properties {
NEW_PROP_TAG (Foo);
NEW_PROP_TAG (Bar);

NEW_TYPE_TAG (BaseTypeTag);
SET_INT_PROP (BaseTypeTag, Foo, 0);
SET_INT_PROP (BaseTypeTag, Bar, 1);

NEW_TYPE_TAG (DerivedTypeTag, INHERITS_FROM(BaseTypeTag));
SET_INT_PROP (DerivedTypeTag, Foo, 2);
}}

int main() {
    Ewoms::Properties::printValues<TTAG (BaseTypeTag)> ();
    Ewoms::Properties::printValues<TTAG (DerivedTypeTag)> ();
    std::cout << GET_PROP_VALUE (TTAG (DerivedTypeTag), Foo)
                << std::endl;
    return 0;
}
```

- 5 The Property System
- 6 The Parameter System**
- 7 Validation against DuMu^x
- 8 Demo: ebos
- 9 Summary & Outlook

- eWoms properties (and C++ traits) must be set at compile time
- The eWoms parameter system deals with values which ought to be specified at runtime:
 - The type of parameters are specified at compile time
 - For each parameter, an eWoms property with exactly the same name must exist
 - The value of the property is used as default for the parameter
 - Parameters must be registered before their value can be retrieved
 - Guarantees the help message to be comprehensive
 - Same parameter can be registered multiple times
 - Description and type specification needs to be identical

In `lensproblem.hh`:

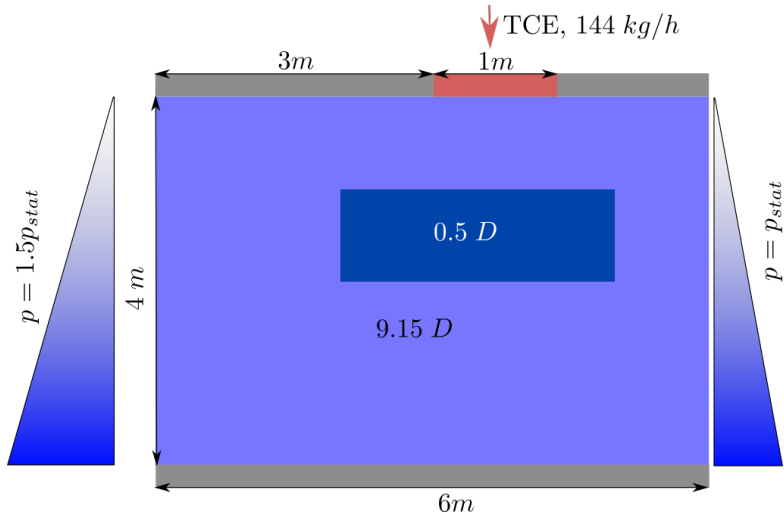
```
static void registerParameters()
{
    EWOMS_REGISTER_PARAM(TypeTag, Scalar, LensLowerLeftX,
                          "Lower-left x of the lens [m].");
};

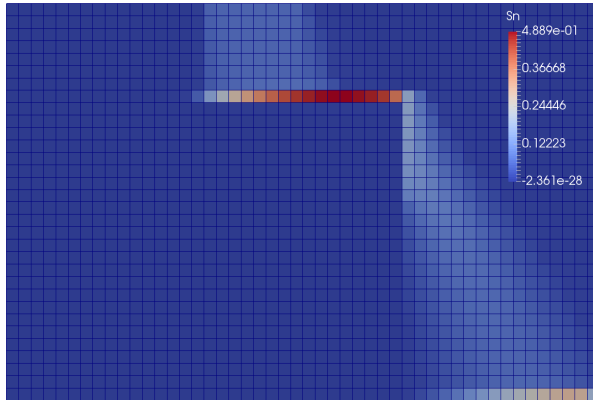
void finishInit()
{ // ...
    lensLowerLeft_[0] =
        EWOMS_GET_PARAM(TypeTag, Scalar, LensLowerLeftX);
};
```

- 5 The Property System
- 6 The Parameter System
- 7 Validation against DuMu^x**
- 8 Demo: ebos
- 9 Summary & Outlook

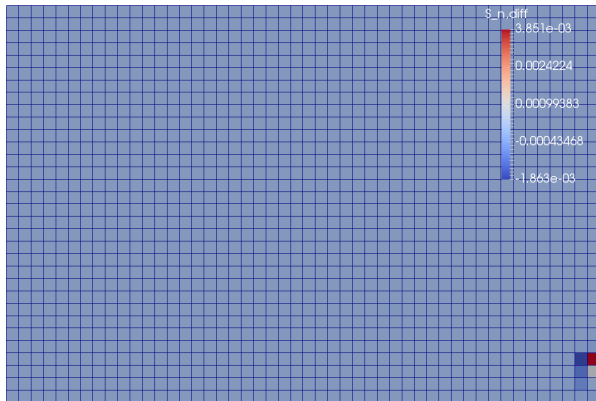
The Lens Problem

Simple yet relevant setup from ground remediation:





Non-wetting phase saturation after 8 hrs, 20 mins

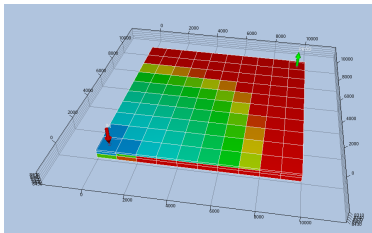


Difference of final non-wetting phase saturation between eWoms and DuMu^X
(~ 25 time steps)

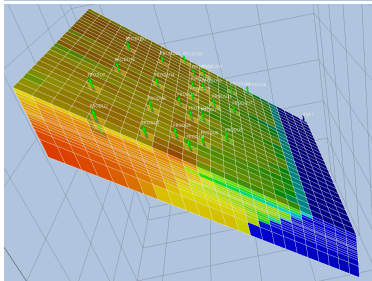
Results of DuMu^X and eWoms basically identical!

- 5 The Property System
- 6 The Parameter System
- 7 Validation against DuMu^x
- 8 Demo: ebos**
- 9 Summary & Outlook

- The **Ecl Black-Oil Simulator**
- Implemented as a standard eWoms problem
- The core of `flow` is a (relatively) thin wrapper around `ebos`
 - Initially a proof of concept for localized linearization with dense automatic differentiation
 - Well model, high-level control code and disk output code derived from `flow_legacy`



SPE-1



SPE-9

- 5 The Property System
- 6 The Parameter System
- 7 Validation against DuMu^x
- 8 Demo: ebos
- 9 Summary & Outlook

- eWoms/ebos constitute the core of the flow reservoir simulator
- eWoms is extremely flexible and can be quite performant
- Unfortunately, eWoms thus is also somewhat complex
- Many things are done differently than in other frameworks

Some things are set to be improved or added in the medium term future:

- Documentation, in particular introductory guides
- Unification of ebos and flow
- Performance is quite good, but has not been a prime focus yet
- Python scripting

Some things are set to be improved or added in the medium term future:

- Documentation, in particular introductory guides
- Unification of ebos and flow
- Performance is quite good, but has not been a prime focus yet
- Python scripting

Thank you for your attention.